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#include "src/GeomParameters.hpp"
#include "TGeoManager.h"
#include "TGLViewer.h"
#include "TGLCamera.h"
#include "TGLPerspectiveCamera.h"

Bool_t Build_Geom(const TGeoManager* geoManager);
Bool_t BuildFields(const TGeoManager* geoManager);

using namespace GeomParameters;

// -----
Int_t sourcetube_geom()
{
    // Load project's shared library (see $ROOTALIAS for function definition)
    gSystem->Load("libUCN.so");
    // Create the geoManager
    TGeoManager* geoManager = new TGeoManager("GeoManager","Geometry Manager");
    // Build and write to file the simulation and visualisation geoms
    Build_Geom(geoManager);
    // Draw Geom
    TCanvas* geomCanvas = new TCanvas("GeomCanvas","Canvas for visualisation of EDM
Geom",60,40,200,200);
    geomCanvas->cd();
    double camera[3] = {0., 0., 0.};
    Analysis::Geometry::DrawGeometry(*geomCanvas, *geoManager, camera);
    // Build Fields
    // Comment this out if you do not want Magnetic, eklectric or gravitational fields to be
created.
    BuildFields(geoManager);
    return 0;
}

// -----
Bool_t Build_Geom(const TGeoManager* geoManager)
{
    // -----
    // BUILDING GEOMETRY
    // Materials - Define the materials used. Leave the neutron properties to be defined on a run-by-
run basis

    Materials::BuildMaterials(geoManager);
    TGeoMedium* beryllium = geoManager->GetMedium("Beryllium");
    TGeoMedium* blackhole = geoManager->GetMedium("BlackHole");
    TGeoMedium* heliumII = geoManager->GetMedium("HeliumII");

    // -----
    // -- Making Top Volume
    Box* topShape = new Box("Top",100,100,100);
    BlackHole* top = new BlackHole("Top", topShape, blackhole);
    geoManager->SetTopVolume(top);
}

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top->SetVisibility(kFALSE);

// -- Make the boundary volume in which all the others sit
// -- This is what we will be reflecting off all the time
Double_t surfaceRoughness = 0.1;
Box* chamberShape = new Box("Chamber",10,10,10);
Boundary* chamber = new Boundary("Chamber", chamberShape, beryllium, surfaceRoughness);
chamber->SetLineColor(kOrange-7);
chamber->SetLineWidth(1);
chamber->SetVisibility(kFALSE);
chamber->SetTransparency(80);
// Add to geom
top->AddNode(chamber,1);

// -----
// -- SOURCE TUBE
// -- Source tube has 13 segments, all of which are identical (except one which has a hole in the top)

// -- Make a SourceTube Segment
Tube *sourceSegShape = new Tube("SourceSeg", sourceSegRMin, sourceSegRMax,
sourceSegHalfLength);
TrackingVolume* sourceSeg = new TrackingVolume("SourceSeg", sourceSegShape, heliumII);
sourceSeg->SetLineColor(kAzure-4);
sourceSeg->SetLineWidth(1);
sourceSeg->SetVisibility(kTRUE);
sourceSeg->SetTransparency(20);

Double_t segmentYPosition = sourceSegYPos;
for (Int_t segNum = 1; segNum <= 13; segNum++) {
    // -- Define SourceTube matrix
    // Rotation seems to be applied before translation so bear that in mind when choosing which
    // coordinate to transform in translation
    TGeoRotation segmentRot("SegmentRot",sourceSegPhi,sourceSegTheta,sourceSegPsi); // phi,
theta, psi
    TGeoTranslation
    segmentTra("SegmentTra",sourceSegXPos,segmentYPosition,sourceSegZPos); // x, y, z
    TGeoCombiTrans segmentCom(segmentTra,segmentRot);
    TGeoHMatrix segmentMat = segmentCom;
    Char_t sourceMatrixName[20];
    sprintf(sourceMatrixName, "SourceMatrix%d", segNum);
    segmentMat.SetName(sourceMatrixName);
    chamber->AddNode(sourceSeg, segNum, new TGeoHMatrix(segmentMat));
    segmentYPosition += 2.*sourceSegHalfLength; // Shift next segment along by length of
segment
}

// -----
// -- SOURCE VALVE
// Valve entrance volume is a shorter source-tube segment-like that connects
// the valve volume to the source
Tube *valveVolEntranceShape = new Tube("ValveVolEntrance", valveVolEntranceRMin,

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valveVolEntranceRMax, valveVolEntranceHalfLength);
    TrackingVolume* valveVolEntrance = new TrackingVolume("ValveVolEntrance",
valveVolEntranceShape, heliumII);
    valveVolEntrance->SetLineColor(kTeal-3);
    valveVolEntrance->SetLineWidth(1);
    valveVolEntrance->SetVisibility(kTRUE);
    valveVolEntrance->SetTransparency(20);
// -- Define the Valve volume entrance
TGeoRotation
valveVolEntranceRot("ValveVolEntranceRot",valveVolEntrancePhi,valveVolEntranceTheta,valveVo
lEntrancePsi);
TGeoTranslation
valveVolEntranceTra("ValveVolEntranceTra",valveVolEntranceXPos,valveVolEntranceYPos,valve
VolEntranceZPos);
TGeoCombiTrans valveVolEntranceCom(valveVolEntranceTra,valveVolEntranceRot);
TGeoHMatrix valveVolEntranceMat = valveVolEntranceCom;
chamber->AddNode(valveVolEntrance, 1, new TGeoHMatrix(valveVolEntranceMat));

// -----
// -- Close Geometry
geoManager->CloseGeometry();

// -----
// -- Write out geometry to file
const char *fileName = "sourcetube_geom.root";
cerr << "Simulation Geometry Built... Writing to file: " << fileName << endl;
geoManager->Export(fileName);

return kTRUE;
}
/*
//_
/// Use this method to include GRAVITY and a MAGNETIC FIELD from an input map.
/// The Field map should have 6 columns of data of the form
/// x(m) y(m) z(m) Bx(T as 0.000000n) By(T as 0.000000n) Bz(T as 0.000000n)
///_
Bool_t BuildFields(const TGeoManager* geoManager)
{
    cout << "-----" << endl;
    cout << "Building Fields" << endl;
    cout << "-----" << endl;
// -----
// -- Gravitational Field
GravField* gravField = new GravField(-1.0,0.0,0.0);
printf("Gravitational Field - nx: %.4f \t ny: %.4f \t nz: %.4f\n",gravField->Nx(),gravField-
>Ny(),gravField->Nz());

// -----
// -- Create a Magnetic field and write it to file

    /// Input field map of name magfilename
string magfilename = "runs/SourceTubeStudies/06_08_10_MattsT2_Map.txt";

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/// Define shape and size of field
TGeoShape* magFieldShape = new Box("FieldShape",10, 10, 10);
/// Define transformation that locates field in local geometry (in this case TGeoMatrix hvcellmat
is used)
TGeoMatrix* fieldMatrix = static_cast<TGeoMatrix*>(geoManager->GetListOfMatrices()->FindObject("hvcellmat"));
cout << "here" << endl;
TGeoMatrix* magFieldPosition = new TGeoHMatrix(*fieldMatrix);
cout << "and here" << endl;
MagFieldMap* field = new MagFieldMap("Field", magFieldShape, magFieldPosition);
cout << "and here 2" << endl;
if (field->BuildMap(magfilename) == kFALSE) {
    Error("BuildFieldMap","Cannot open file: %s", magfilename);
    return kFALSE;
}
// Add field to magfield manager
MagFieldArray* magFieldArray = new MagFieldArray();
magFieldArray->AddField(field);

// -----
// -- Write magfieldmanager to geometry file
const char *outputFileName = "runs/SourceTubeStudies/sourcetube_fieldsIncMag.root";
TFile *file = Analysis::DataFile::OpenRootFile(outputFileName, "recreate");
gravField->Write(gravField->GetName());
magFieldArray->Write(magFieldArray->GetName());
file->Close();
delete gravField;
delete magFieldArray;
return kTRUE;
}

/*
// -----
// Use this method to include only GRAVITY.
// -----
Bool_t BuildFields(const TGeoManager* geoManager)
{
    cout << "-----" << endl;
    cout << "Building Fields" << endl;
    cout << "-----" << endl;
    // -----
    // -- Gravitational Field
    GravField* gravField = new GravField(-1.0,0.0,0.0); // Pointing down the X-Axis for this geom
    printf("Gravitational Field - nx: %.4f \t ny: %.4f \t nz: %.4f\n",gravField->Nx(),gravField->Ny(),gravField->Nz());
    // -- Write fields to file
    const char *fieldsFileName = "sourcetube_fields.root";
    TFile *file = Analysis::DataFile::OpenRootFile(fieldsFileName, "recreate");
    cout << "Fields Created... Writing to file: " << fieldsFileName << endl;
    gravField->Write(gravField->GetName());
    file->Close();
}

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// Cleanup
delete gravField;
return kTRUE;
}

/*
-----Build gravitational and Magnetic (from file) Fields -----
// _____
Bool_t BuildFields(const TGeoManager* geoManager)
{
    cout << "-----" << endl;
    cout << "Building Fields" << endl;
    cout << "-----" << endl;
// -----
// -- Gravitational Field
GravField* gravField = new GravField(-1.0,0.0,0.0);
printf("Gravitational Field - nx: %.4f \t ny: %.4f \t nz: %.4f\n",gravField->Nx(),gravField-
>Ny(),gravField->Nz());

// -----
// -- Create a Magnetic field and write it to file
string magfilename = "runs/SourceTubeStudies/25_Apr_2012_Phil_Map.txt";
// Define shape of field
TGeoShape* magFieldShape = new Box("FieldShape", 100, 100, 100);
// Define transformation that locates field in geometry
TGeoMatrix* fieldMatrix = static_cast<TGeoMatrix*>(geoManager->GetListOfMatrices()->FindObject("segmentMat"));
TGeoMatrix* magFieldPosition = new TGeoHMatrix(*fieldMatrix);
MagFieldMap* field = new MagFieldMap("Field", magFieldShape, magFieldPosition);
    cout << "and here" << endl;
if (field->BuildMap(magfilename) == kFALSE) {
    Error("BuildFieldMap","Cannot open file: %s", magfilename);
    return kFALSE;
}
// Add field to magfield manager
MagFieldArray* magFieldArray = new MagFieldArray();
    cout << "here too" << endl;
magFieldArray->AddField(field);

// -----
// -- Write magfieldmanager to geometry file
const char *outputFileName = "runs/SourceTubeStudies/sourcetube_fieldsIncMag.root";
TFile *file = Analysis::DataFile::OpenRootFile(outputFileName, "recreate");
gravField->Write(gravField->GetName());
magFieldArray->Write(magFieldArray->GetName());
file->Close();
delete gravField;
delete magFieldArray;
return kTRUE;
}/*

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